

## TITLE OF THE INVENTION

Fiber Optic Temperature Sensor

## CROSS REFERENCE TO RELATED APPLICATIONS

This application claims priority under 35 U.S.C. §119(e) of U.S. Provisional Patent Application No. 60/428,099 filed November 21, 2002, the disclosure of which is hereby incorporated by reference herein.

STATEMENT REGARDING FEDERALLY SPONSORED RESEARCH OR  
DEVELOPMENT

This invention was made with Government support under contract no. N00014-97-G011 awarded by the Department of the Navy, and from the Air Force Office of Scientific Research, under contract number \_\_\_\_\_. The Government has certain rights in the invention.

## BACKGROUND OF THE INVENTION

The present invention relates to the field of temperature measurement devices and techniques based on optical technology.

In many high temperature processes, it is important to have accurate knowledge of temperature, for example to maximize efficiency. This is true for processes such as materials processing in the metal and glass industries, and is equally true in the measurement of turbine inlet temperatures in jet engines and in stationary gas turbine power plants. However, the maximum temperatures in these processes can reach as high as 1,700 to 2,300° C. Ordinary thermocouples cannot meet the requirements for stable and accurate operation in such high-temperature applications.

It has been shown that temperature sensors based on optical technology may be employed to achieve certain benefits

not possessed by conventional thermocouples. An optical thermocouple includes a silica glass fiber, one end of which terminates in a so-called fiber Bragg grating. In one known configuration, the fiber Bragg grating is composed of alternating layers of silicon nitride and silicon-rich silicon nitride. The fiber Bragg grating responds to changes in temperature by corresponding changes in the spectral content of reflected light, specifically by a change in the optical wavelength at which peak reflectivity occurs. This response can be exploited for use in an optical temperature measurement system.

A measurement system can be built in which broadband optical energy is transmitted along an optical fiber toward one end at which a fiber Bragg grating is formed. The fiber Bragg grating is disposed in an environment whose temperature is to be measured. A broadband optical spectrum analyzer is also coupled to the fiber to receive optical energy reflected from the fiber Bragg grating. By analyzing the output from the optical spectrum analyzer, it is possible to determine the amount of wavelength shift of the peak of the reflectivity characteristic, and then to convert this peak shift into a temperature value.

Optical-based temperature measurement systems such as those described above have several advantages, including the ability to withstand high temperatures and immunity from electrical noise due to their all-dielectric construction. With respect to temperature, however, silica-based fiber and fiber Bragg gratings are generally limited to use at temperatures less than about 1,100° C. It would be desirable to have an optical-based measurement system that permits the measurement of much higher temperatures such as those encountered in the industrial and turbine applications described above.

## BRIEF SUMMARY OF THE INVENTION

In accordance with the present invention, a fiber optic temperature sensor and system are disclosed that achieve the benefits of optical temperature sensing at much higher temperatures than have heretofore been possible, thus enabling the accurate measuring of temperature in a variety of high-temperature applications.

The disclosed sensor and system employ optical fiber and fiber Bragg gratings using non-silica materials that can withstand temperature ranges well above the silica-imposed limit of 1,100° C. In one embodiment, the use of sapphire optical fiber enables use of the sensor at temperatures approaching 1,800° C, while an alternative sensor employing yttria-stabilized zirconia is capable of use at temperatures in excess of 2,350° C. These high-temperature fibers are used in conjunction with fiber Bragg gratings made of materials that can also withstand such temperatures. In one case, the grating employs alternating layers of yttria stabilized zirconia, with the percentage of yttria varying in the alternating layers to achieve the desired difference of refractive index. Alternatively, alternating layers of alumina and zirconia can be employed.

The dynamic range of this device is extremely wide, and can be as low as liquid nitrogen temperatures. Unlike black body or pyrometer type devices, there is no dependence upon limiting low photon flux at low temperatures.

Other aspects, features, and advantages of the present invention will be apparent from the Detailed Description that follows.

## BRIEF DESCRIPTION OF THE SEVERAL VIEWS OF THE DRAWINGS

The invention will be more fully understood by reference to the following Detailed Description of the invention in conjunction with the Drawing, of which:

Figure 1 is a block diagram of an optical temperature measurement system in accordance with the present invention;

Figure 2 is a cross-sectional view of a high-temperature optical probe used in the measurement system of Figure 1;

Figure 3 is a plot of representative curves of reflectance versus wavelength for a fiber Bragg grating such as used in the optical probe of Figure 2;

Figure 4 is a plot of representative values of wavelength peak shift versus temperature for a fiber Bragg grating such as used in the optical probe of Figure 2;

Figure 5 is a flow diagram of a process for converting raw optical spectrum data from an optical spectrum analyzer into a temperature value in the measurement system of Figure 2; and

Figure 6 is a plot illustrating the calculation of a fine part of wavelength shift in the process of Figure 5.

## DETAILED DESCRIPTION OF THE INVENTION

Figure 1 illustrates a temperature measurement system employing an optical-fiber-based probe 10 disposed in a high-temperature environment 12. The high-temperature environment 12 may exhibit a temperature range from  $-200^{\circ}\text{C}$  to  $2,350^{\circ}\text{C}$ , the upper end of which is considerably higher than the maximum temperatures that may be directly measured using conventional means. Examples of such high-temperature environments 12 include material processes (such as the manufacture of ceramics), gas turbine inlet streams (such as jet engines or power plants), rocket nozzle exhaust streams, and space applications, etc.

Extending from the probe 10 is an optical fiber 14. An optical coupler 16 joins the probe fiber 14 to two additional fibers 18, 20. The fiber 18 carries light from a broadband light source 22 to the probe 10 via the coupler 16, and the fiber 20 carries reflected light from the probe 10 to an optical spectrum analyzer (OSA) 24, which may be for example a charge-coupled device (CCD) array. The electrical outputs of the OSA 24 are coupled to a digital processor 26.

The broadband light source 22 can be implemented by a LED or other suitable broadband source. The range of optical wavelengths from the source 22 encompasses a range of reflectance frequencies of a fiber Bragg grating employed within the probe 10, which is described in more detail below.

Figure 2 shows the probe 10 in detail. The optical fiber 18 is encased in a flexible metal jacket 27 and extends into a probe body including an outer sleeve 28 of ceramic or metal, an elongated inner ceramic sleeve 30, and an inner quartz sleeve 32. The ends of the probe body are sealed with high temperature cement 34. The optical fiber 18, which is typically silica, is butt-joined to a tip optical fiber 34 of a material capable of withstanding extremely high temperatures. Examples of such a material include sapphire and yttria-stabilized zirconia. Preferably the fibers 18 and 34 are coupled using an anti-reflective coating to reduce undesirable optical reflections and losses.

Formed at the distal end of the tip optical fiber 34 is a  $1/4$ -wavelength fiber Bragg grating 36, which is used as a wavelength-selective reflector. The grating can be made using different types of ceramic systems. In one scheme, the grating 36 is made using yttria-stabilized zirconia, with alternating layers having different concentrations of yttria to achieve the small difference of refractive index that is required for a narrow reflecting structure. The percentage of yttria doping can

be from, typically, 5% to 40%. This structure retains its chemical stability when subjected to temperatures as high as 2400° C. Also, the thermal expansion properties of such layers are well matched, minimizing destructive thermal-induced mechanical strain. This is extremely important.

As an alternative, alternating layers of alumina and zirconia can be employed. It may be desirable to add yttria to the zirconia layers to improve the refractive index matching between the two layers. A layer having 20% yttrium has a refractive index of 1.9, which is close to the refractive index of 1.76 of alumina.

The grating 36 can be formed using a process in which a layer is deposited at the end of the fiber 18 while the reflectance at a particular wavelength is monitored. The reflectance will vary between a maximum and a minimum as each layer is deposited. When a peak or valley of the reflectance is reached during the deposition of one layer, the deposition is stopped and the deposition of the next layer is begun. This process is repeated until the desired number of layers have been deposited.

Additionally, it is possible to form the grating 36 using other combinations of repeating sequences of materials of different refractive indices that will provide high reflectivity over a narrow wavelength region.

Figure 3 generally illustrates the variation of reflectance with temperature of a fiber Bragg grating such as grating 36. The particular curves shown in Figure 3 are representative of a fiber Bragg grating employing alternating layers of silicon nitride and silicon-rich silicon nitride, but it is expected that similar results will be obtained for fiber Bragg gratings of the type described above.

As shown in Figure 3, the reflectance of the grating at a given temperature will exhibit a peak at a particular

wavelength. In Figure 3, the peak reflectivity is about 84%. The horizontal location of this peak will shift as the temperature of the grating changes. This is shown in Figure 3 as a horizontal shifting of the reflectance-versus-wavelength curve. It is also shown in Figure 4 as a scatter plot of peak shift versus temperature, under conditions of heating as well as cooling. The vertical units of Figure 4 are CCD pixels in the OSA 24. It will be observed from Figure 4 that the dependence of peak shift on temperature is almost linear, and exhibits almost no hysteresis. In the example shown in Figure 3, the peak occurs at about 840 nm at 25° C, and shifts to approximately 855 nm at 1100° C. By measuring the amount of the peak shift from some predetermined calibrated position, the temperature of the grating, and thus of the environment immediately surrounding the grating, can be accurately determined.

Figure 5 shows a process for obtaining temperature measurements from the probe 36 based on the peak shift of reflected light. In step 38, the probe 36 is placed in an environment of known temperature, and the characteristic spectrum data is obtained from the OSA 24, normalized, and saved as a reference spectrum. This normalization takes the following form:

$$\tilde{Y} = \frac{(N+1)\tilde{X} - \sum_{i=0}^N x_i}{\sqrt{\sum_{i=0}^N \left( (N+1)x_i - \sum_{i=0}^N x_i \right)^2}}$$

where X represents the raw spectrum data vector and Y represents the normalized data vector. To facilitate subsequent processing, only the main portion of the spectrum containing the peak is utilized. This vector can be represented as

$$\mathbf{A}=[a_1, a_{i+1}, \dots, a_{i+N})$$

In step 40, measured spectrum data is obtained at an unknown temperature being measured, and this data is normalized using the same normalization function described above. To facilitate the analysis steps to follow, the normalized measured spectrum data is saved as an array of sub-vectors of the overall vector output of the OSA 24. These can be represented as follows:

$$\mathbf{B}_0=[b_1, b_{i+1}, \dots, b_{i+N})$$

.

$$\mathbf{B}_k=[b_{i+k}, b_{i+k+1}, \dots, b_{i+k+N})$$

.

$$\mathbf{B}_m=[b_{i+m}, b_{i+m+1}, \dots, b_{i+m+N})$$

where m represents an assumed maximum pixel shift of the measured characteristic spectrum, which corresponds to the highest temperature to be read by the probe 36.

At step 42, the "whole" part h of the spectrum peak shift (in integer number of pixels or CCD elements) is determined using a least squares algorithm on the reference and measured spectrums. This involves computing a measure of the difference between the normalized reference spectrum vector and each of the normalized measured spectrum vectors, and then determining which of the computed difference values is the smallest. This algorithm can be expressed as follows:

1. For k = 0 to k = m, calculate:

$$\begin{aligned} d_k &= (\mathbf{A} - \mathbf{B}_k)^* (\mathbf{A} - \mathbf{B}_k) \\ &= \sum_{n=0}^N (a_i - b_{i+k+n})^2 \end{aligned}$$

2. Find the minimum  $d_k$ , which is denoted  $d_h$ . The value h is the whole part of the peak shift.



In step 44, the fractional part  $t$  of the peak shift is determined. This preferably uses an "extreme value" calculation, which is described with reference to Figure 6. Figure 6 shows the relationship of several values used in the calculation, namely  $a_i$ ,  $b_i$ ,  $a_{i+1}$ ,  $b_{i+1}$ , etc. The calculation uses the following equation:

$$t = \frac{\sum_{n=0}^N [(a_{i+n} - b_{i+h+n})(b_{i+h+n+1} - b_{i+h+n})]}{\sum_{n=0}^N (b_{i+h+n+1} - b_{i+h+n})^2}$$

Finally, in step 46, the spectral shift is calculated as

$$S_{\text{shift}} = W_{\text{pixel}} * S_{\text{pixel}},$$

where

$$S_{\text{pixel}} = h + t$$

and  $W_{\text{pixel}}$  is equal to the per-pixel spectral width of the OSA 24. If linearity is assumed, the value  $W_{\text{pixel}}$  can be calculated by dividing the total spectral width of the OSA 24 by the number of pixels (CCD elements) in the array.

The value  $S_{\text{shift}}$  can then be translated to a temperature using a pre-computed conversion factor obtained during a calibration process. This factor has units of degrees/(nm of wavelength), and thus yields a temperature in degrees when multiplied by  $S_{\text{shift}}$ . In one type of calibration process, the steps of Figure 5 are performed at two temperatures of known separation, and the conversion factor is then calculated by dividing the known temperature separation by the value of  $S_{\text{shift}}$  that is obtained in the measurement process. For example, a reference measurement can be taken at 25° C, and a second measurement taken at 50° C, providing a known 25° C difference in temperature. This value is divided by the value of  $S_{\text{shift}}$  obtained for the second measurement to obtain the conversion

factor. It will be appreciated that other techniques for obtaining a conversion factor or a set of conversion factors to be used for temperature measurements can be employed, which might account for non-linearities in the temperature-vs.-wavelength characteristic of the system.

As an example of the use of the conversion factor, if it is assumed that the conversion factor is 15° C per nm, then a value of  $S_{\text{shift}} = 37.6$  yields a measured temperature T of

$$\begin{aligned} T &= 25 + (15)(37.6) \\ &= 589^{\circ} \text{ C} \end{aligned}$$

It will be apparent to those skilled in the art that modifications to and variations of the disclosed methods and apparatus are possible without departing from the inventive concepts disclosed herein, and therefore the invention should not be viewed as limited except to the full scope and spirit of the appended claims.